

Voice Controlled Robot Car

Ms. Sonali Samadhan Bagal, Ms. Aishwarya Umesh Nalwade, Ms. Ishwari Govind Shelke

UG Scholars, Department of Electronics and Telecommunication Engineering

SVERI's College of Engineering, Pandharpur, Maharashtra, India

Abstract: *In this studies paper, a system is being proposed, which makes a speciality of the idea of the way a robot can be controlled by way of the human voice. Voice manipulate robot is simply a sensible example of controlling motions of a simple robotic by giving each day used voice commands. In this system, an android app is used as a medium for the transmission of human commands to microcontroller. A controller can be interfaced with the Bluetooth module via the UART protocol. The speech is received by using the android app and processed via the voice module. Voice is then converted to textual content. [1] The microcontroller will similarly technique this newsletter, that allows you to take suitable movement to adjust the robotic. The objective is to layout a robot car whose simple actions including transferring ahead, turning to left or proper can be managed via the human voice. The Hardware Development board used here is the ATmega Arduino board. The software program part is carried out in Arduino IDE the usage of Embedded C. Hardware is applied, and software program porting is achieved. Generally, reputation of human voice using a few kind of module cost manner too much. After performing an sufficient quantity of studies on controlling robots, we got here to the conclusion that yes, there exists a easy and very efficient manner to govern robots thru our voice. This is an ergonomic technique for the ease of robotic utility. Such types of robots will provide brilliant assisting fingers whilst performing a couple of tasks. The result of our research also shows that there nonetheless exists plenty of area for further studies.*

Keywords: Ultrasonic Sensors, Arduino, Bluetooth Module- HC05, Motor Driver, BO Motors, Android App, Servo Motor

I. INTRODUCTION

Mainly it behaves to been a fancy soul to elevate approximately system which agree with like as human beings. Recognizing the speech and respondent therefore may be a critical part of this fancy. Including the improvements of the terminology and exploration on spurious rational, this fancy flip real relatively. This task aim is to get an essential position for make contributions the fancy. Dominant the device and surroundings such as oration create mortal life easiest and lightest. The challenge can be a smooth shaping of this shelter. Those voice is acquired with the aid of the arm which methods and send to the robotic for very last output. Basically, speech used to manner of the humans. Under the developments of communicate technology within the ultimate length, that the speech starts to be a crucial for many approaches. More than used raised finally numerous interfaces, speech is certainly to conversation with computers.

II. METHODOLOGY

2.1 Bluetooth module HC05

Pros – HC-05 Bluetooth Module is an smooth to use Bluetooth SPP (Serial Port Protocol) module, designed for transparent wi-fi serial connection setup.

Cons - Although maximum cellular gadgets and plenty of PCs nowadays aid Bluetooth, the generation comes with a few risks, inclusive of slow records speeds, poor facts security and shortened battery lifestyles.

Applications -Wireless communication is unexpectedly replacing the stressed-out connection in relation to electronics and communique. Designed to replace cable connections HC-05 makes use of serial conversation to speak with the electronics. Usually, it is used to attach small devices like cell phones the usage of a short-variety wireless connection to alternate documents. It uses the 2.45GHz frequency band. The switch price of the data can vary as much as 1Mbps and is in range of 10 meters.

The HC-05 module can be operated within four-6V of strength supply. It supports baud price of 9600, 19200, 38400, 57600, and many others. Most importantly it may be operated in Master-Slave mode this means that it will neither send or receive information from external resources. Programming HC-05 with Microcontroller

Technical specifications of the code:

Arduino-Uno is used as the microcontroller.

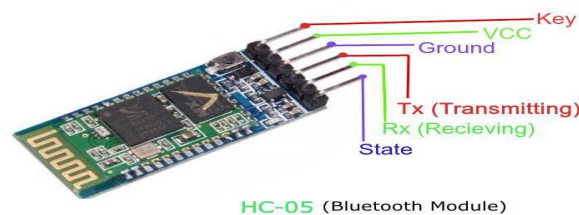
Name: HC-05

Password: 1234 (or 0000)

Type: Slave

Mode: Data

Baud Rate: 9600 with eight records bits, no parity and 1 forestall bit



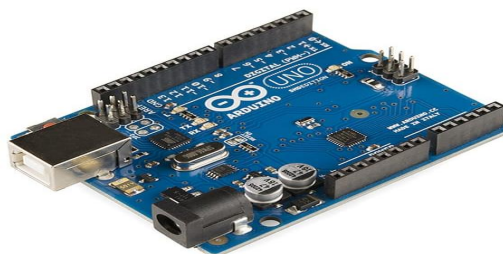
2.2 Arduino Uno

Pros – Arduino has a few advantages, inclusive of big user community, free and wide tiers of libraries of codes, relatively low-price additives, easy to learn and so on.

Cons – Its risks are its small and a consumer has to work in a notably small (or as a substitute tiny) space. In many wide and multi-reason tasks, its required to search for 0.33 party assets similarly to Arduino scripts. Another disadvantage is that during many instances, some mistakes remain quite persistent and mistakes messages might not be pretty useful.

Applications – Arduino uno is used in home automation, industrial automation, embedded systems.

Arduino UNO is a microcontroller board based at the ATmega328P. It has 14 virtual input/output pins (of which 6 may be used as PWM outputs), 6 analog inputs, a 16 MHz ceramic resonator, a USB connection, a power jack, an ICSP header and a reset button. It consists of the entirety had to support the microcontroller; really connect it to a pc with a USB cable or power it with a AC-to-DC adapter or battery to get commenced. You can tinker along with your UNO without annoying an excessive amount of about doing something incorrect, worst case scenario you may replace the chip for some dollars and start another time.



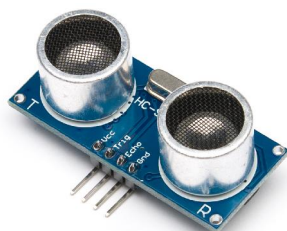
2.3 Ultrasonic

Pros – No moving parts, compact, reliable, not affected by media properties

Cons – expensive, invasive, performance can be affected by various elements in the environment

Applications – Non contact applications with highly viscous and bulk solids. Used in systems that require remote monitoring

Ultrasonic sensors measure levels by calculating the duration and strength of high frequency sound waves that are reflected off the surface of the liquid and back to the sensor – the time taken is relative to the distance between the sensor and the liquid. The length of time in which the sensor takes to react is affected by various elements in the atmosphere above the media such as turbulence, foam, temperature etc. Hence why the mounting position is critical in these devices.



2.4 Motor Drivers

Pros -Capable of giving high voltage.

Cons – we cannot control 4 motors at a time only 2 motors can be controlled.

Applications - Motor drivers act as an interface between the motors and the manage circuits. Motor requires excessive quantity of modern-day while the controller circuit works on low contemporary signals. So, the feature of motor drivers is to take a low-current manage sign and then turn it right into a higher-current sign that may drive a motor.



2.5 Servo motor



Pros – High performance.

High output energy relative to their size.

More regular torque at higher pace.

Closed-loop manipulate.

Quiet operation.

Highly dependable.

High ratio of torque to inertia.

High acceleration.

Cons - Servos Motors requires tuning to stabilize the feedback loop.

Servo Motor becomes unpredictable when some thing breaks. ...

Complex controller calls for encoder and electronic help.

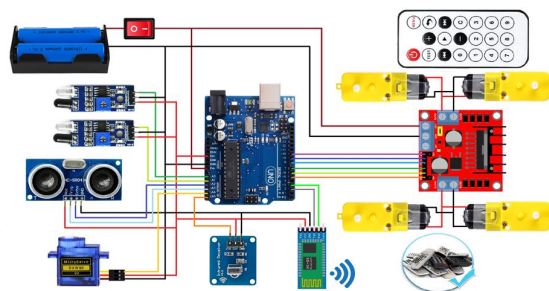
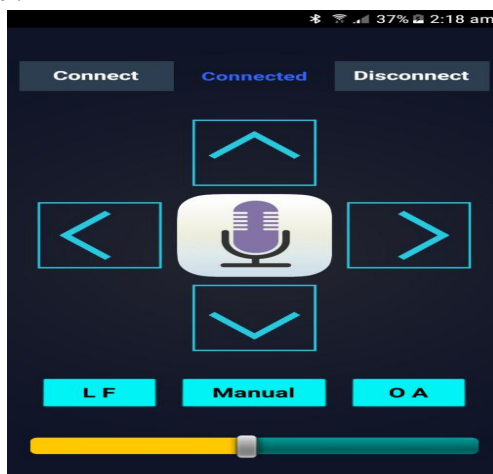
Peak torque is restrained to a 1% obligation cycle.

III. WORKING PRINCIPLE

The controlling device can be any android primarily based Smartphone/tab and many others having an android OS. The android controlling gadget presents a great interactive GUI that makes it easy for the consumer to control the automobile.

The transmitter uses an android utility required for transmitting the records. The receiver gives up reads these commands and translates them into controlling the robot automobile. The android tool sends commands to move the vehicle in forward, backward, right and left guidelines.

After receiving the commands, the microcontroller then operates the cars I order to transport the automobile in 4 directions. The conversation among android tool and receiver is dispatched as serial verbal exchange data. The microcontroller program is designed to transport the motor thru a motor driver IC as in keeping with the instructions dispatched by means of android tool.



IV. APPLICATIONS

Wheel Chair: Mainly to function our challenge the robotic is controlled by means of a giving a selected instructions in amr voice apps. From giving the commands the robotic might be flow stop.

Home Automation: Nowadays due to a good deal maximum cheap and simplicity at some point of smartphones and tab connectivity respectively. Recently the popularities of the home automation growing greatly in recent years.

Military Appliances: Our robotic is mobile robotic which plays an important function in navy topics. With the precise sensor and smooth digital camera these robots are operated. All the work could be the corporations are getting without difficulty from the cellular robotic.

V. CONCLUSION

The voice-controlled commands are successful transmitted through Bluetooth generation and on reception the preferred operations efficaciously take area. This project reduce human efforts at locations or state of affairs wherein human interventions are tough. Such systems can be brought into use at locations which includes industries, military and defense and so on.

FUTURE SCOPE

The major item such robotic gadget is to help individuals with motor disabilities it controlling completely. In future time we use a secured wireless channel the usage of mystery writing and cryptography. There are many scope may be held in destiny along with AI movements speech to textual content translation and lots of additional. It additionally be in agricultural scope to moreover develop under artificial intelligence

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