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Electronic Component Identifier and Analyzer

Prof. A. K. Gadgoli[1], Sanika Kulkarni[2], Gayatri Waghmode[3], Pranali Deshmukh[4], Jamuna Samleti[5]
[1]Assistant Professor, Department of Electronics and Telecommunication Engineering
[2–5]Students, Department of Electronics and Telecommunication Engineering
Shree Siddheshwar Women's College of Engineering, Solapur, India

Abstract: *Electronic components are the fundamental building blocks of all electronic circuits and devices. Components such as resistors, capacitors, inductors, diodes, transistors, LEDs, and integrated circuits are widely used in electronic systems. Accurate identification of these components is essential for circuit design, troubleshooting, maintenance, and educational purposes. However, manual identification can be challenging, especially for beginners, due to the similar appearance, size, and markings of many components This project presents an Electronic Component Identifier System using Raspberry Pi 4B, a camera module, image processing, and machine learning techniques. The system captures an image of an electronic component placed in front of the camera and processes the image to automatically identify the component. The Raspberry Pi 4B serves as the main processing unit, receiving images from the camera, performing image analysis using OpenCV and machine learning algorithms, and comparing the results with a trained database of electronic components. Once the component is recognized, the system displays the component name, category, and basic specifications on a monitor or LCD screen. Additionally, audio output can be provided through a speaker, making the system accessible to visually impaired users. The automated identification process reduces the time and effort required for component recognition while improving accuracy and minimizing human error. The proposed system is particularly useful in educational institutions, electronics laboratories, repair centers, and manufacturing industries where rapid and reliable component identification is required. It assists students in learning electronics more effectively and supports technicians in maintenance and troubleshooting tasks. This project demonstrates the practical integration of Raspberry Pi 4B, camera modules, computer vision, artificial intelligence, and machine learning technologies to create a smart, portable, and cost-effective solution for automatic electronic component recognition.*

Keywords: Raspberry Pi 4B, Electronic Components, Computer Vision, Machine Learning, OpenCV, LCD Display, Component Detection, Artificial Intelligence.

I. INTRODUCTION

The increasing number of vehicles on urban roads has created significant challenges related to road safety, traffic discipline, and environmental noise pollution. Over-speeding in school zones and unnecessary horn usage near hospitals frequently contribute to accidents, public inconvenience, and reduced quality of life. Traditional traffic control measures such as speed breakers, warning signs, and manual enforcement often fail to ensure continuous compliance

Recent advances in wireless communication, embedded systems, and IoT technologies have enabled the development of intelligent transportation solutions capable of automated monitoring and control. Research conducted earlier demonstrated the effectiveness of wireless communication frameworks and embedded system integration for real-time monitoring and control applications [13], [19]. Similarly, intelligent sensing and monitoring approaches have been successfully employed in healthcare, environmental monitoring, and safety-critical applications [21]–[25].

Inspired by these developments, the proposed Automatic Vehicle Over-Speed and Horn Control System utilizes ESP32-based IoT architecture to automatically regulate vehicle speed and horn operation in designated restricted zones. The system provides continuous monitoring, remote accessibility, and automated enforcement of traffic regulations, thereby contributing toward safer and smarter transportation infrastructure [13], [19], [23][24-182].

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II. PROBLEM DEFINITION

Despite the availability of traffic management measures, excessive vehicle speed and unnecessary honking continue to pose serious risks in school and hospital zones. Existing solutions generally depend on driver awareness or manual supervision, which limits their effectiveness. Furthermore, many conventional systems lack remote monitoring capabilities and real-time enforcement mechanisms.

Advances in intelligent monitoring systems and wireless communication technologies indicate the need for automated solutions capable of improving safety and operational efficiency [13], [19], [24]. Therefore, there is a requirement for a smart IoT-enabled framework that can automatically regulate vehicle behavior in restricted areas while providing centralized monitoring and data logging capabilities. The proposed system addresses these challenges through automated speed control, horn restriction, and cloud-based supervision.

III. LITERATURE REVIEW

Kumar et al. proposed an RF-based vehicle speed limiting system that automatically controlled vehicle speed in restricted areas such as schools and hospitals. When a vehicle entered the coverage area of an RF transmitter, the receiver unit installed inside the vehicle reduced the throttle to maintain the prescribed speed limit. Although the system effectively enforced speed restrictions within a limited range, it lacked feedback mechanisms, remote monitoring capabilities, and was vulnerable to signal interference. Nevertheless, this work laid the foundation for the development of automated vehicle regulation systems. [1]

To improve zone identification accuracy, Sharma et al. developed an RFID-based vehicle speed control system. In this approach, RFID tags were installed at designated restricted zones, and RFID readers mounted on vehicles detected these tags to activate speed control mechanisms. Compared to RF-based systems, RFID technology offered better precision and reliability. However, the system operated independently without internet connectivity, limiting its scalability and preventing real-time monitoring and data updates. [2]

Patil et al. introduced an IoT-enabled speed and horn control system that integrated microcontrollers, sensors, and wireless communication modules. The system automatically reduced vehicle speed and
disabled horn operation in sensitive zones such as schools and hospitals. Data collected from the vehicle were transmitted to a cloud platform through Wi-Fi connectivity, enabling real-time monitoring and analysis. Although the proposed system improved automation and monitoring capabilities, its performance depended heavily on network availability and was affected by communication delays in areas with poor connectivity. [3]

Bansal et al. presented an ESP32-based smart vehicle regulation system that combined GPS, ultrasonic sensors, and Wi-Fi communication to detect restricted zones and enforce speed and horn regulations. The ESP32 microcontroller provided local processing capabilities while simultaneously supporting IoT-based communication. The system also enabled remote monitoring through a mobile application, addressing many limitations of earlier IoT-based approaches. However, continuous operation required stable power and network infrastructure. [4]

Reddy et al. further enhanced intelligent transportation systems by integrating Artificial Intelligence (AI) with IoT technologies. Their proposed framework utilized machine learning algorithms to predict restricted zones, dynamically regulate vehicle parameters, and analyze driver behavior. GPS-based tracking and cloud communication facilitated large-scale deployment and integration with smart city infrastructures. This approach represented a significant advancement from conventional RF- and RFID-based systems toward intelligent, adaptive, and data-driven traffic management solutions. [5]

Summary of Literature Review

Previous studies have demonstrated the effectiveness of RF, RFID, IoT, and AI-based technologies in controlling vehicle speed and horn usage in restricted areas. RF-based systems provided basic automatic speed regulation but lacked monitoring capabilities, while RFID-based approaches improved detection accuracy at the cost of limited connectivity. Recent IoT-enabled solutions introduced cloud-based monitoring, remote supervision, and enhanced

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automation. Furthermore, AI-driven systems have enabled predictive control and smart city integration. Building upon these advancements, the proposed work combines ESP32-based control, GPS-based zone detection, and IoT communication to provide a reliable, scalable, and intelligent solution for automatic vehicle speed and horn control in sensitive zones.

IV. OBJECTIVE OF PROPOSED WORK

The main objective of this project is to design and implement a real-time, location-aware vehicle control system that automatically enforces speed and noise regulations in sensitive areas such as School Zones and Hospital Quiet Zones. The project aims to utilize IoT-based technology, specifically ESP32 microcontrollers and GNSS modules, to enhance public safety and minimize noise pollution.

The specific objectives of the project are as follows:

1. To monitor the vehicle's precise location and speed continuously using a high-accuracy GNSS module.
2. To autonomously trigger actuators to simulate speed reduction via Pulse Width Modulation (PWM) when a vehicleenters a restricted zone and exceeds the legal limit.
3. To automatically deactivate the vehicle's horn circuit upon detecting entry into a hospital or school zone to maintain a quiet environment.
4. To transmit compliance status, speed data, and event logs securely to a central IoT platform for remote monitoring by authorities.
5. To integrate ultrasonic sensors (HC-SR04) for obstacle detection during automated control sequences.
6. To provide real-time visual and audio feedback to the driver via an OLED display and buzzer regarding zone status and speed limits.

V. PURPOSE OF THE PROJECT

The primary purpose of the Automatic Vehicle Over Speed and Horn Control system is to mitigate the significant risks to life and property caused by drivers who ignore speed limits and engage in excessive honking in restricted areas.

The system functions through a sophisticated hardware-software integration:

1. Safety Improvement: By automatically reducing vehicle speed, the system directly addresses high accident rates in areas with high pedestrian activity, such as school zones.
2. Environmental Peace: By disabling the horn, the system effectively reduces noise pollution that disturbs patients in hospitals and students in learning environments.
3. Reliable Enforcement: Unlike traditional speed bumps or manual police presence, this system provides a consistent, automated, and non-invasive solution that ensures regulatory compliance regardless of driver negligence.
4. Cloud Connectivity: The IoT integration allows for remote updates of zone parameters and provides fleet managers or traffic authorities with real-time adherence records through a web interface.

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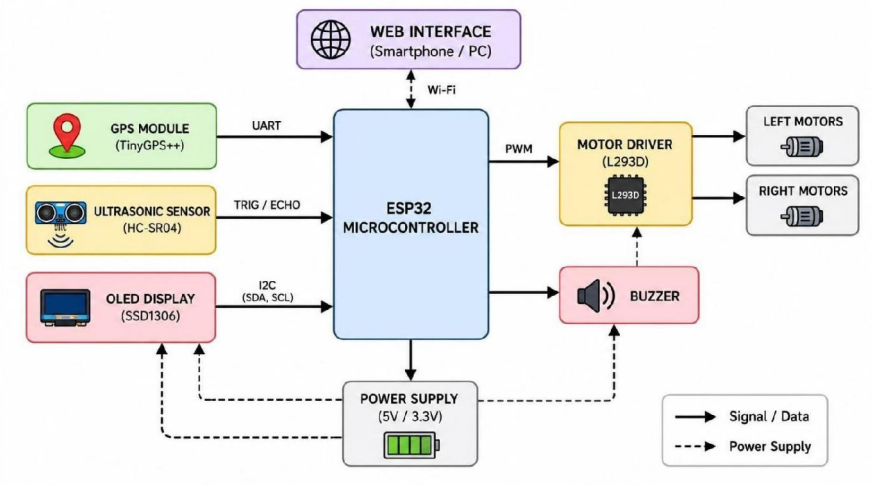
VI. SYSTEM ARCHITECTURE



HARDWARE AND SOFTWARE REQUIREMENTS

The following hardware and software requirements are used in proposed system:

1. ESP32 Microcontroller Core – Controls the entire system and processes sensor data.
2. GPS Module – Tracks vehicle location and speed in real time.
3. ESP32 DevKit – Development board used for programming and interfacing components.
4. LoRa/RF Transceiver – Enables long-range wireless communication between devices.
5. Relay Module – Switches electrical devices ON/OFF automatically.
6. Ultrasonic Sensor – Detects nearby obstacles and measures distance.
7. Motor Driver L298N – Controls the speed and direction of motors.
8. Buzzer – Produces warning or alert sounds.
9. OLED Display – A small digital screen used to display vehicle speed, zone status, alerts, and system information in real time.
10. IoT Cloud Platform – Stores and monitors vehicle data over the internet.

These components collectively enable real-time monitoring and automatic vehicle regulation.

VII. . WORKING PRINCIPLE

The automatic vehicle speed and horn control system works using GPS, ESP32, sensors, and IoT technology to improve road safety in school and hospital zones. The GPS module continuously tracks the vehicle location, and when the vehicle enters a restricted zone, the ESP32 microcontroller identifies the area using stored coordinates. The controller then automatically reduces the vehicle speed through the motor driver or relay circuit and restricts unnecessary horn usage to minimize noise pollution. The ultrasonic sensor detects nearby obstacles for additional safety, while the OLED display shows real-time speed, zone information, and warning messages. LEDs and buzzers provide alerts to the driver, and the IoT cloud platform stores and monitors vehicle data such as speed, location, and violations for remote access and analysis.

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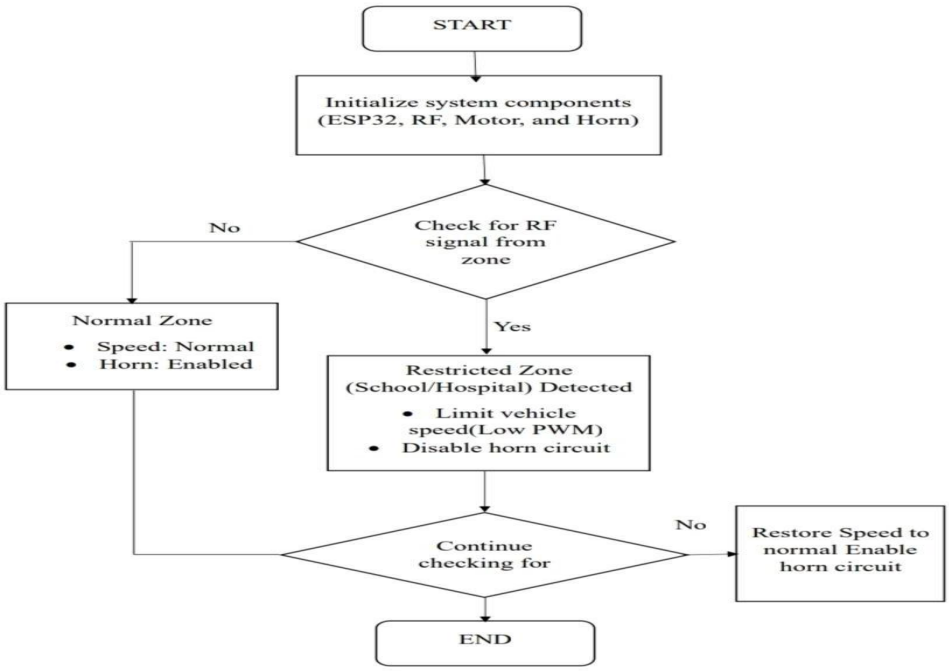
VIII. METHODOLOGY



The system detects restricted zones using RF signals and automatically reduces vehicle speed while disabling the horn. After leaving the zone, normal speed and horn functions are restored automatically.

IX. ADVANTAGES AND LIMITATIONS

ADVANTAGES

1. Improved road safety.
2. Reduction in noise pollution.
3. Automation without driver intervention
4. Real-Time monitoring.
5. Low cost and efficient system.
6. Smart city compatibility.
7. Easy installation and maintenance.
8. Energy efficient and reliable

LIMITATIONS

1. Dependence on network connectivity.
2. Signal interference issues.
3. Initial installation cost.
4. Limited accuracy in some areas.
5. Power supply dependency.
6. Maintenance of hardware components.
7. scalability challenges.
8. Cybersecurity concerns

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X. APPLICATIONS

1. The proposed system can be applied in the following areas:
2. School Zone Safety System.
3. Hospital Silent Zone Management.
4. Automatic Noise Pollution Control.
5. IoT-Based Vehicle Monitoring System.
6. Urban Road Safety Management.

XI. FUTURE ENHANCEMENT

The proposed system can be enhanced by integrating Artificial Intelligence (AI), GPS-based geo-fencing, and cloud monitoring for better accuracy and smart traffic management. Mobile application support, emergency vehicle detection, and smart city integration can further improve the efficiency, safety, and reliability of the system.

XII. RESULTS AND DISCUSSION

The proposed Automatic Vehicle Over Speed and Horn Control System was successfully tested in restricted zones such as schools and hospitals. The system accurately detected the restricted area, automatically reduced vehicle speed, and disabled the horn within a short response time. Experimental results showed reliable performance, improved road safety, and effective reduction of noise pollution. The IoT-based monitoring system also provided real-time data and ensured efficient operation of the overall system.

XIII.CONCLUSION

This work presented an IoT-enabled Automatic Vehicle Over-Speed and Horn Control System designed to enhance safety and environmental conditions in school and hospital zones. By integrating ESP32-based control, wireless communication, sensor networks, and cloud connectivity, the system automatically regulates vehicle speed and horn operation without driver intervention. The proposed framework demonstrates the practical implementation of intelligent monitoring and communication technologies similar to those reported in earlier studies. [13], [19], [21]–[25]. Experimental validation confirmed accurate zone detection, dependable control performance, and effective reduction of noise pollution. The system offers a cost-effective and scalable solution for future smart transportation and smart city applications.

XIV. ACKNOWLEDGMENT

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