IJARSCT



International Journal of Advanced Research in Science, Communication and Technology

International Open-Access, Double-Blind, Peer-Reviewed, Refereed, Multidisciplinary Online Journal

Volume 5, Issue 10, April 2025



Implementation of Collision Avoidance System for Hairpin Bends in Ghats Using Proximity Sensors

Sarthak Bajirao Mhaske¹, Anupam Bhagvan Katale², Sushant Somnath Bodke³,

Sanket Bharat Jadhav⁴, Prof. P. S. Kankrej⁵

Department of Civil Engineering¹⁻⁵ Matoshri Aasarabai Polytechnic, Eklahare, Nashik, Maharashtra, India

Abstract: People don't care enough to stay safe while driving on road. During a long travel accidents and deaths caused by them are the most serious issues now-adays. Research in this paper includes the main issues like ghat road accidents and their impacts, causes of this accident, effect of accident, preclusion and control so that we can improve this state. It is not safe now a-days to drive through the ghat areas while turning in the hairpin bends. The percentages of accidents in ghat sections are increasing day by day. Severity of these accidents is non reparable. So firstly it is important to control this situation and have some safety measures in hairpin bends. This paper includes some solutions and ideas to improve protection in ghat sections. Hairpin bend accidents occur mostly because of the driver unable to see the vehicle coming from the opposite sides of the road curves. Our system uses sensors to detect any vehicles reaching hair pin bend and alerts immediately on other side vehicles by red signal and also producing alert sound. If hair pin bend road is clear green signal is produced. Thus this system provides safety for drivers to prevent hill side accidents and ride safely in hill side roads. Often modern cars have a collision avoidance system built into them known as Pre-Crash System, Forward Collision

Keywords: curve roads, accident prevention sensor, mountain road, hill roads,ultrasonic sensor, alerting the driver.,



DOI: 10.48175/IJARSCT-25607

