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A Comprehensive Framework for Human-Robot Collaboration in Industrial Environments

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Abstract: Human-robot collaboration (HRC) has emerged as a promising paradigm for enhancing productivity and efficiency in industrial settings. To ensure the successful implementation of HRC, a comprehensive framework is necessary to address the technical, social, and organizational challenges involved. This paper proposes a framework that encompasses four key componentsSafety and Risk Management, Human-Robot Interaction Design, Organizational Integration, and Ethical Considerations. The framework emphasizes the importance of conducting thorough risk assessments, adhering to safety standards, and developing emergency response plans. It also highlights the need for intuitive interfaces, optimized task allocation, and ergonomic considerations in human-robot interaction. Moreover, the framework addresses the organizational challenges associated with HRC, including training, change management, and workplace redesign. Finally, it emphasizes the ethical implications of HRC, such as job displacement, privacy concerns, and accountability. By adopting this framework, organizations can maximize the benefits of HRC while minimizing risks and ensuring a harmonious coexistence between humans and robots in the workplace. The proposed framework provides a valuable resource for businesses seeking to implement HRC successfully and reap the rewards of this emerging technology.

Keywords: Human-robot cooperation (HRC), industrial robots, robotics, automation, risk assessment, emergency response, safety standards (ISO 10218, ISO/TS 15066), and human-robot interaction (HRI)

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