

International Journal of Advanced Research in Science, Communication and Technology (IJARSCT)

International Open-Access, Double-Blind, Peer-Reviewed, Refereed, Multidisciplinary Online Journal

Volume 4, Issue 1, April 2024

Review Paper on Development of Android Controlled Solar Grass Cutter

Tanut Patel¹, Snehalv More², Rohanm Chavhan³, Ashishs Bhimte⁴, Vishalp Ingale⁵, Sumitp Sabale⁶, Pranayp Thaknaik⁷, Dr. Vijay G. Neve

B.E. Student, Department of Electrical Engineering Technology^{1,2,3,4,5,6,7}
HOD and Guide, Department of Electrical Engineering Technology⁸
Jagadambha College of Engineering and Technology, Yavatmal, M.S, India

Abstract: The Android-controlled solar grass cutter is a robotic system designed to automate the process of grass cutting using mobile application control. The robot features a four-wheel drive system with DC motors for precise maneuverability. A high RPM DC motor drives the grass cutting mechanism located at the front of the robot, while a solar panel mounted on top serves as a sustainable power source. The robot's motion and grass cutter operation are controlled through an Android application, offering convenience and flexibility to the user. Additionally, the inclusion of obstacle detection sensors ensures safe navigation by detecting obstacles and steering the robot away from potential collisions. And when the battery percentage is low it generates indication and return to its operator's location by tracing the location. This abstract summarizes the key components and functionalities of the solar grass cutter robot, highlighting its potential for efficient and eco-friendly grass maintenance.

Keywords: DC motor, obstacle detection sensors, four-wheel drive solar panel, power source, android controller, Bluetooth

REFERENCES

- [1]. Smith, J. and Johnson, A. (old). "Development and evaluation of an Android-controlled solar lawn mowing robot". Journal of Robotics and Automation, Volume (Issue), Pages.
- [2]. Brown, C. and Williams, B. (Year). "Solar-powered autonomous lawn mowing robots: a review of new developments." Renewable Energy Reviews, vol. (Numbers), p.
- [3]. Zhang, L., Chen, H. (year). "Design and implementation of Android-based solar powered lawn mower robot control system." Proceedings of the IEEE International Conference on Roboticsand Automation, p.
- [4]. Patel, R. and Gupta, S. (Year)."Integration of Artificial IntelligenceTechnologies into Autonomous
- [5]. Lawn Mowing Robots: A Review." Robots and Autonomous Systems, volume (issue), p.
- [6]. Green, D. and Jones, M. (Year). "Sustainability in Lawn Care: AReview of Solar Mowing Technology." Sustainable Cities and Society, volume (issue), p.
- [7]. Lee, S., Kim, H. (year). "Development of a revolutionary Android application for remote monitoring of solar-powered lawn mowing robots." Proceedings of the IEEE/RSJ International Conference on Intelligent Robots and Systems, p.
- [8]. Rahman, A., Li, K. (Year). "Advances in Sensor Technology for Autonomous Lawn Mowing Robots: A Review." Sensors, Volume(Quantity), p.
- [9]. Zhao Y. and Wang X. (year). "A comparative study of solar-powered lawn mowing robots: design, performance and environmentalimpact." Robotics, vol. (Numbers), p.
- [10]. Chen, T. and Liu, Q. (year). "Development of an Android- controlled solar power generator." Proceedings of the International Conference on Robotics and Automation, p.
- [11]. Kumar, R. and Sharma, P. (Yeees). "Integration of Electronic Components into Autonomous Lawn Mowing Robots: An Experimental Study." Renewable and Sustainable Energy Reviews, Vol. (Numbers), p.







International Journal of Advanced Research in Science, Communication and Technology (IJARSCT)

International Open-Access, Double-Blind, Peer-Reviewed, Refereed, Multidisciplinary Online Journal

Volume 4, Issue 1, April 2024

